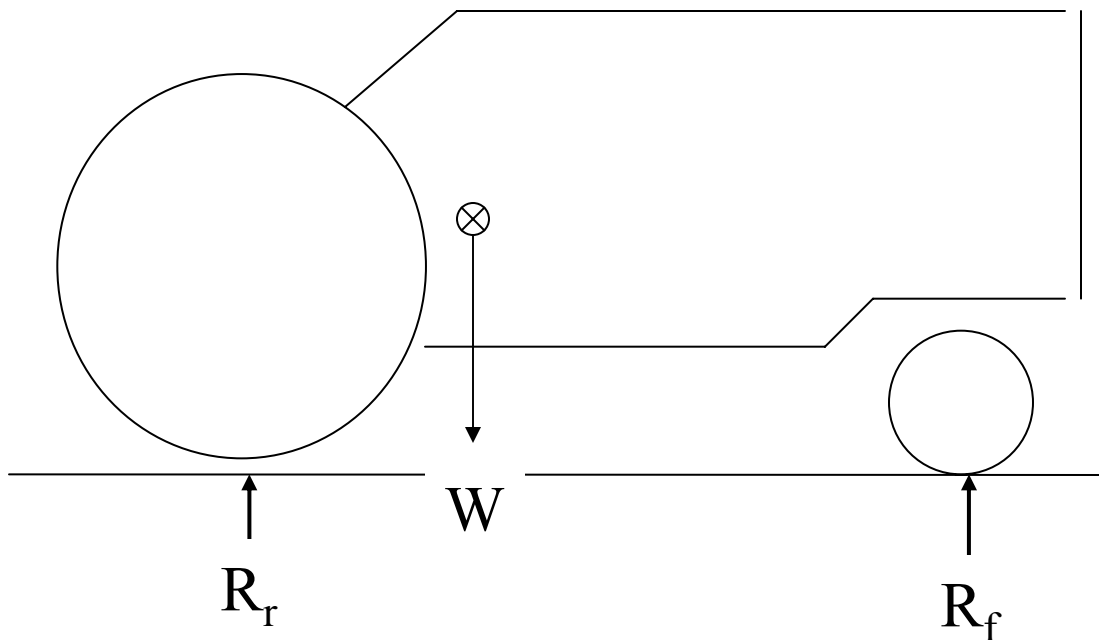
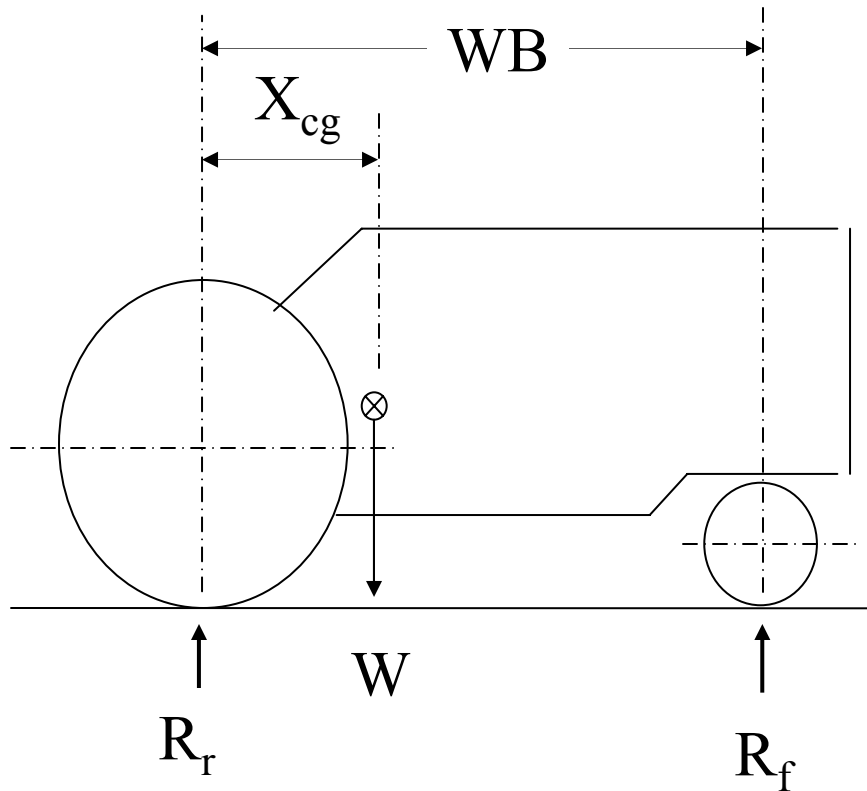


# Weight Transfer, Traction & Stability

- Moments and Center of Gravity
  - ⇒ The center of gravity can be determined using moments about any point on the tractor
  - ⇒ For the tractor to be in equilibrium the clockwise moment must equal the anti-clockwise moment
    - $\text{Moment} = \text{Force} * \text{Perpendicular distance to line of force}$



# Center of Gravity



- **Moments about rear axle**

Clockwise Moment = CounterClockwise Moment

$$W * X_{cg} = R_f * WB$$

$$\Rightarrow X_{cg} = R_f * WB / W$$

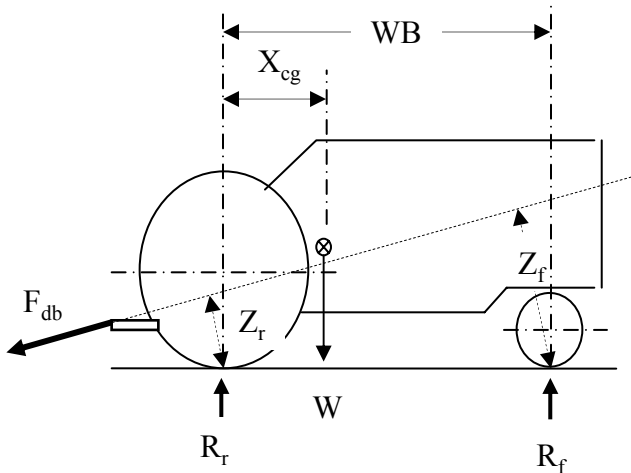
Metric

$$X_{cg} \text{ (mm)} = R_f \text{ (kN)} * WB \text{ (mm)} / W \text{ (kN)}$$

English

$$X_{cg} \text{ (in)} = R_f \text{ (lb.f)} * WB \text{ (in)} / W \text{ (lb.f)}$$

# Weight Transfer



## Moments about rear axle: Dynamic Front Wheel Reaction

Clockwise Moment = CounterClockwise Moment

$$W * X_{cg} = R_f * WB + F_{db} * Z_r$$

$$\Rightarrow R_f = (W * X_{cg} - F_{db} * Z_r) / WB$$

## Moments about Front axle: Dynamic Rear Wheel Reaction

Clockwise Moment = CounterClockwise Moment

$$R_r * WB = W * (WB - X_{cg}) + F_{db} * Z_f$$

$$\Rightarrow R_r = [W * (WB - X_{cg}) + F_{db} * Z_f] / WB$$

### Static Reaction Forces

Drawbar Pull = 0

Front

$$R_{fo} = (W * X_{cg}) / WB$$

Rear

$$R_{ro} = [W * (WB - X_{cg})] / WB$$

### Dynamic Reaction Forces

Drawbar Pull =  $F_{db}$

Front

$$R_f = (W * X_{cg} - F_{db} * Z_r) / WB$$

Rear

$$R_r = [W * (WB - X_{cg}) + F_{db} * Z_f] / WB$$



### Dynamic Weight Transfer

$\Delta R = \text{Dynamic Forces} - \text{Static}$

Front



$$\Delta R_f = (R_{fo} - R_f) = -(F_{db} * Z_r) / WB$$

Rear



$$\Delta R_r = (R_{ro} - R_r) = F_{db} * Z_f / WB$$

# Basic Concepts of Traction: Travel Reduction

- Travel Reduction (TR): Reduction in actual forward speed that occurs due to increased slippage when the drawbar load is increased. Theoretically, Slip and Travel reduction are not identical although they are often used interchangeably.

$$TR = 100 * (1 - S_a / S_o)$$

where:  $S_a$  = Actual travel Speed,  $S_o$  = Travel Speed on specified surface with no load

- Travel reduction must occur to develop drawbar pull
  - ⇒ Tire lug must compress the soil allowing it to develop tractive force
  - ⇒ Rear movement results in travel reduction

# Basic Concepts of Traction: Tractive Force

- Gross Tractive Force Coefficient ( $\mu_g$ ): Gross Tractive Horizontal Force (F) divided by the Dynamic Weight (Reactive Force) on driving wheel.

$$\mu_g = F/W = 0.75*[1 - \exp(-0.3C_n S)]$$

$$C_n = CI \text{ bd}/W$$

- Motion Resistance Ratio ( $\rho$ ): Horizontal Towing Force (TF) divided by the Dynamic Weight (Reactive Force) on wheel.

$$\rho = F/W = 1.2/C_n + 0.04$$

$$C_n = CI \text{ bd}/W$$

- Net Tractive Force Coefficient ( $\mu$ ): Net Tractive Horizontal Force (H) divided by the Dynamic Weight (Reactive Force) on driving wheel.

$$\mu = H/W = (F - TF)/W = 0.75*[1 - \exp(-0.3C_n S)] - [1.2/C_n + 0.04]$$

$$C_n = CI \text{ bd}/W$$

# Basic Concepts of Traction: Dynamic Traction Ratio

- Dynamic Traction ratio (DTR) is the ratio of drawbar pull ( $F_{db}$ ) over the dynamic weight on the driving wheels

$$DTR_{(2 \text{ wheel Drive})} = F_{db} / [ R_{ro} + \Delta R_r ]$$

where:  $R_{ro}$  is static weight on rear wheels and  $\Delta R_r$  is weight transfer

- A high DTR needed for high drawbar pull
  - Improved lug design
  - Radial ply design
- Increase weight will also increase pull at the cost of higher compaction and increased stress on the axles

# Basic Concepts of Traction: Tractive Efficiency

- Tractive Efficiency (TE) is the fraction of axle power ( $P_a$ ) that is converted to drawbar power ( $P_{db}$ ) by the drive wheels

$$TE = P_{db} / P_a$$

$$TE = [F_{db} * V] / P_a$$

Metric

$$TE = [F_{db}(\text{kN}) * V(\text{km/h}) * 1000(\text{m/km}) / 3600(\text{sec/h})] / [P_a(\text{kW})]$$

$$TE = [F_{db}(\text{kN}) * V(\text{km/h})] / [P_a(\text{kW}) * 3.6 (\text{km/h per m/s})]$$

English

$$TE = [F_{db}(\text{lb.f}) * V(\text{mph}) * 5280(\text{ft/m}) / 60(\text{sec/h})] / [P_a(\text{Hp}) * 33000(\text{ft.lb/min per Hp})]$$

## Basic Concepts of Traction: Tractive Efficiency

- $TE = P_{db} / P_a$

$$P_{db} = [F_{db} * V_a]$$

$$\Rightarrow TE = [F_{db} * V_a] / P_a$$

$$P_a = T\omega \quad \begin{array}{l} T = \text{Axle Torque} \\ \omega = \text{angular velocity} \end{array}$$

$$\Rightarrow TE = [F_{db} * V_a] / T\omega$$

$$\Rightarrow TE = [F_{db} * V_a] / [(F * r) * (V_t / r)]$$

$$\omega = V_t / r \quad r = \text{rolling radius}$$

$$\Rightarrow = [H / F] * [V_a / V_t]$$

$$T = F * r \quad F = \text{Gross Traction}$$

$$F_{db} = H \text{ (Net Traction)}$$

$$\Rightarrow TE = [H / F] * [1 - S]$$

$$V_a / V_t = (1 - S) \quad S = \text{Slip}$$

$$\Rightarrow TE = [(H/W) / (F/W)] * [1 - S]$$

$$\Rightarrow TE = [(\mu_g - \rho) / \mu_g] * [1 - S]$$

# Travel Reduction, Drawbar Pull and Maximum Tractive Efficiency

- Drawbar Pull
  - Zero Slip, Zero Drawbar Pull
  - 100% Slip, Max Drawbar Pull
- Dynamic Traction Ratio
  - Zero Slip, DTR=0
  - 100% Slip, DTR=maximum

- Tractive Efficiency

$$TE = \text{Tractive} / \text{axle Power}$$

$$\text{Tractive Power} = \text{Drawbar Force} * \text{Velocity}$$

## Zero Slip

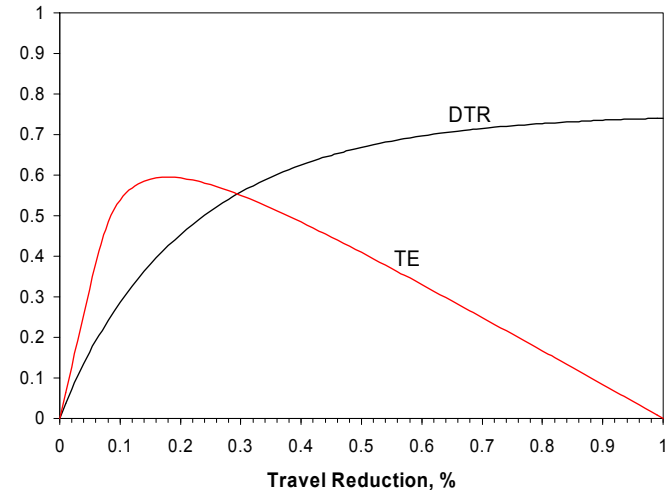
Velocity=maximum, Drawbar Force =0

⇒ Tractive Power =0, TE=0

## 100% Slip

Velocity=0, Drawbar Force =maximum

⇒ Tractive Power =0, TE=0



**Figure 1: Variation of Tractive Efficiency and Dynamic Traction Ratio with travel reduction for a particular tractor on one specific soil**

Maximum tractive efficiency occurs at some intermediate slip conditions, generally between 10-15%, but will depend on the conditions.